New Frontiers in the remote sensing of clouds

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Outline:

•Reflect on The three eras of cloud remote sensing → why and what I want to observe and some questions posed Remote sensing system → how to observe and typical challenges •A-train multi-sensor study of water clouds, ice clouds Observing the warm rain process The next step •Summary

~1970

The first phase: a period of great imagination and some enlightenment



The first 24hr view of global clouds TIROS-9, February 13, 1965

The launch of TIROS-1, April 1960





A period when we gathered qualitative data opening new global vistas on clouds - the information content, however, remained low ... but this sort of 'imagery' motivated the birth of ISCCP in 1978



Ë



First flight of precipitation radar, TRMM, 1997







The third phase: grand challenge – integrating information → parameter to process



2000

Since mid 2006, we have access to a wide range of different sensors, active and passive, optical, infrared and microwave, hyper-spectral to coarse band, all approximately viewing Earth at the same time. We are left to pose a strategy that optimally combines these measurements, providing deeper insights on critical 'water system' processes.



Two pertinent questions to such feedbacks that remote sensing can assist in answering: Given circulation and clouds, what of fluxes and heating? Given the heating, what of circulation and clouds? These feedbacks also involve processes that connect the microphysical scale up to the 'climate' scale



important climate processes

The real frontier

We now consider that clouds and precipitation (and aerosol too??) are part of a continuum of connected processes. Much understanding has been thwarted through a general artificial separation of cloud science and precipitation science. The real opportunities lie in studying/observing processes that lie at the the intersection of the two.

The pathway to improved prediction of precipitation, global and regional, will be through improved prediction of clouds and their evolution.

Cloud and precip structures







CloudSat global precipitation products are under construction, - the PIA product illustrated here is describe in Haynes et al., 2008 and is to be released to the sci team b4 the August meeting

Precipitation over global oceans

20 - 4 15 -- 3 CTL (km) Top height of 10^{*} 10 precipitating clouds 5 -- 1 0 0 2 3 R (mm/hr) 0 5 1 4

Challenges in representing rainfall.....



Seasonal JJA precipitation incidence

Ellis et al., 2008

Accumulation



Main elements of a remote sensing observing system

- Platform, determines the representativeness of the observations (e.g. geostationary and the time/space sample as in ISCCP)
- Experimental design ie the physical basis of the method, the instrument, a priori knowledge data bases, models, etc...

The Remote Sensing Observing System



The forward model contains a number elements – a model of the atmosphere, a model of the measurement and an inverse model. The roles of assumptions and parameters involved are often grossly overlooked when assessing the capability of the remote sensing observing system.

The influence of the atmospheric model on the retrieved state is generally overlooked



So clearly observations that better constrain the 'atmospheric model' will potentially provide dramatic improvements to the retrieval problem (eg CloudSat)



Forward Models are typically based on the following types of physics



(c)

scattering

Passive (radiometry)

These methods provide primarily path integrated information

^{Se} The challenge/opportunity (and perhaps the emerging
'frontier') today is to sensibly exploit observations of cloud
and precipitation parameters that have different
underlying physical bases ...

bulk water mass

Optimizing multiple sources of 'similar' information

Matters to ponder:

Which of the different approaches (& physics) is optimal? How accurate is the retrieved information and What is to be gained in combining different types of measurements ?

Some advantages of multi-sensor data- provides a way of consolidating our understanding: (i)by providing a way of assessing products and component parts of retrieval approaches through comparison – (ii)by providing the opportunity to combine into an integrated and physically consistent retrieval approach

The (scene) identification problem





is it cloud or not?

is it cloud or is it rain?

Multi-sensor Example : the water contents of low clouds

Microwave emission

The difference is related to the absorbing/emitting species along the path mostly water vapor, cloud liquid water, and precipitation



Scattered sunlight

Twomey & Cocks, 1980's Nakajima & King, 1990s



0 0

 $R_2 \rightarrow (1-\omega g)\tau$

optical depth r

- The reflection in the near-IR (R₂) is a function of optical depth τ and the scattering albedo ω the latter is a function of particle size r_e.
- Measurements of reflection at two wavelengths (or spectral bands) returns the pair of parameters τ and r_e



 $R_1 \rightarrow (1-g)\tau$

Do VIS/NIR and PMW estimates of LWP agree?

• Bennartz (2007), Borg & Bennartz (2007), find that, for the NIR observations,

LWP = 2/3 $\rho \tau R_e$ (vertically homogeneous cloud) be replaced with

LWP = $5/9 \rho \tau R_{e,top}$ (adiabatic cloud) for warm stratocumulus clouds.

This leads to good agreement between NIR & PMW LWP for *overcast, stratocumulus clouds*:



For **all warm clouds**, however, there is a distinct positive bias in the PMW at the low end of LWP:



But what about precipitation????

No Precipitation

Precipitating clouds are wetter than nonprecipitating clouds

The particles are larger but there is no obvious 'threshold' precipitation size



Possible

Using MODIS and CloudSat, Stephens et al., 2008



deeper, wetter and brighter than non-raining clouds

1.0



Aerosol indirect effects using A-train obs - Lebsock et al., 2008



We are able to observe the most important aspects of clouds that affect their albedo as such we perhaps can say there appears to be a global Twomey effect and a *correlation* between precipitation probability and aerosol



Aerosols appear to have the biggest impact on clouds formed in a more unstable environment. Comparing the blue and red curves suggests that, in a statistical sense, polluted clouds require higher water contents to precipitate. Example 2: Ice water contents and thin cloud detection Scattering/transmission by lidar, scattering by mm radar

Results from CloudSat & CALIPSO



Thin Ice Cloud (TIC) Type 1 : Only LIDAR can see. Thin Ice Cloud (TIC) Type 2: Both RADAR and LIDAR can see.

Haladay & Stephens, 2008

CloudSat products for TIC-2



This combination identifies the detection thresholds of one Instrument over the other T~0.2



A consistent picture of OD, IWP and particle size



Slope of this curve implies a typical ice effective radius of 40 µm for cirrus.

Using 40 µm effective radius, combined with measured Tau yields an estimate of the distribution of IWP of thin cirrus missed by Cloudsat.

MLS and CloudSat IWC comparisons also paint a similar picture



IWC CloudSat and IWC MLS converted to visible extinction using the same Microphysical assumptions. The sensitivities diverge $\tau \sim 0.2$

Another frontier – probing processes The example of warm rain



When droplets grow by vapor deposition, the mass increases but not the number concentration



When coalescence occurs, big drops grow by collecting little drops - that is the total droplet number concentration is reduced but the total mass of water doesn't change

The warm rain coalescence process



Suzuki and Stephens, 2008

aerosol effects?

Pristine: AI < 0.1 Polluted: Al > 0.1



Another way to view these processes



He mean reflectivitiv relates the the rate of coalescence (Stephens and Haynes, 2008)
CRM model performance



Summary

With the ability now to observe clouds and precipitation jointly and in a variety of different ways, and with an ability to characterize the environment in which clouds form, we are now moving into an era where we may in fact be developing an understanding of how the large-scale environment affects important cloud processes.

This is of central importance to topics like indirect effects, cloud-climate feedbacks

The real frontier Tying remotely sensed information to the bigger picture



It is in this context that we want to be able to place the cloud properties that we remotely sense The previous generation was greatly concerned with the dynamics of pressure systems and talked about highs and lows. Today we have not lost interest in these systems but we tend to look upon them as circulation systems. This change in attitude has led to a deeper understanding of their dynamics. Perhaps the next generation will be talking about the dynamics of water systems.

Lorenz, 1970.

Spaceborne Atmospheric Radars

GPM/DPR – NICT/JAXA

TRMM/PR – NICT/JAXA Ku, Scanning , Tropical Rain

Ku/Ka, Scanning, Precipitation Description Description

ACE Radar W/Ka, Scanning, Doppler



W, -30dBZ, Clouds EarthCARE/CPR - NicryAska Gaigo Aux Order Clouds Order Clouds Order Clouds

CloudSat/CPR – JPL/NASA

1997-Today

May 26-30 2008

The next frontier – sustain active and add capability - Doppler

Better way to discriminate/determine microphysics



Better way to estimate latent heating Dynamics of water systems, etc ...

Enhanced product - precip incidence & amount



Precipitation as a function of CT height



Any given column may contain multiple cloud layers. We defined two quantities:

• CTH - the Cloud Top Height of the Highest Layer

(close to the traditional CTH observed by IR or passive microwave)

• CTL - the Cloud Top Height of the Lowest Layer

(closely connected with the height of the physical portion of the cloud system that is associated with precipitation microphysics)

Results from CloudSat, (II): Global IWP from different cloud types



* Austin, Heymsfield, & Stephens, for submission to JGR, 2008



Global Mean IWP from 2B-CWC-RO (version R04), Dec 2006 – Nov 2007. Cloud types from the 2B-CLDCLASS product. Convective cloud types are shaded. Error bars show the estimated systematic uncertainty.

* Austin, Heymsfield, & Stephens, JGR, 2008

The new frontiers – to bridge the 'scale gap'

Micro-	PV Hobbs	
scale	1km 10km 100km	a E A
← quan	titative 100km	
	quantitative	

Radar Observations - present capabilities and future challenges/needs for ACE

Graeme Stephens, Colorado State University



ACE: What advances over CoudSat and EarthCare?

Radar

- 2 frequency (35/94) Microphysics, precipitation
- Doppler ~0.5m/s conv, 0.3m/s goal uphysics, dynamics, LH.
- Higher vertical resolution 250m 4X? oversampled Shallow BL clouds
- Polarization? Phase, ice microphysics
- higher sensitivity ~-35 dBZ (94) & surface clutter filtering low clouds
- scanning?

- 35/94 GHz radiometry cloud water path, precip; NEDT ~1K?? Lidar

- 2 frequency HSRL

Polarimeter

Unambiguous extinction at 2λ 's \rightarrow aerosol microphysics Aerosol and cloud microphysics, Phase, particle morphology, ...

Other sensors ???

E.g. microwave radiometer, AMSR-E+high frequency

Vertical motion measurement from space



IEEE Radar Conference – Rome May 26-30 2008

Challenges

5) Much more capability for determining the microphysics of clouds, precipitation and aerosol



The combination of Doppler velocities and radar reflectivity measurements provides a way of measuring profiles of ice cloud microphysics with a capability well beyond that available from space today. Measurement requirement minimum resolution accuracy ~0.2m/sec; scale 1-2km for Z>-15 dBZ

Matrosov et al., 200?

Frontier 2: Using combinations of remotely sensed parameters to characterize processes emphasizing cloud-precip transition

 r_e



Fig. 1. Scatter plot between effective particle radius and optical thickness obtained from satellite observation over FIRE (upper) and ASTEX (lower) regions (cited from Nakajima and Nakajima 1995)

Nakajima and Nakajima (JAS 1995)



 τ_c or *LWP*

(1)non-drizzling stage

2 drizzling stage

3evaporating stage

Another example - snow



1/D

With the new observing systems we have an ability to jointly :

Deduce gross information on cloud optical properties

The integrated cloud water I no (& light) rain

The vertical profiles of clouds (thickness,)

Precipitation incidence (and amount)

And we can combine these and begin to examine important cloud-scale physical processes set on a much vaster scale than previously studied



IV. State information, including aerosol and meteorology (motions large & small, thermodynamics ...)

GCSS/WGNE Pacific Cross-section Intercomparison (GPCI)



- GPCI is a working group of the GEWEX Cloud System Study (GCSS) funded by the NASA MAP Program
- Models and observations are analyzed along a transect from stratocumulus, across shallow cumulus, to deep convection
- Models: GFDL, NCAR, UKMO, JMA, MF, KNMI, DWD, NCEP, MPI, ECMWF, BMRC, NASA/GISS, UCSD, UQM, LMD, CMC, CSU, GKSS



Cloud Cover along GPCI



CloudSat cloud occurrence along GPCI



These news obs are being used in quantitative assessment of cloud properties in association with the circulation that defines them

ISCCP and the anatomy of weather systems – the Lau and Crane (1995) example



Bjerknes to Lau and Crane to Cloudsat



38

(b)

40

Front

48

46

Posselt et al., 2008

44

Latitude

42

200 300 400 500 600 700 800 900 (-35,0,-7.5) (-22.5,-5.0) (-10.0,-2.5) (2.5,0.0) (15.0,2.5) (27.5,5.0) A DISTANCE ALONG AB B

thick cloud thin cloud





FIG. 7. As in Fig. 4, but for a portion of Cloudsat granule 3034, observed at approximately 1730 UTC 22 Nov 2006.

Case study example : 26 February 2007

- Analysis chart valid at 12 UTC
- CloudSat overpass at ~14:15 UTC



A case study of frontal systems



Α

Simulators of the observing system are being coupled to climate models as part of the CFMIPII activity which is to support the next IPCC assessment





It not just about processes affecting TOA Radiation balance





Convection = precipitation

+

Radiative heating/stabiliza tion

High clouds

.... what establishes global precipitation changes clouds here also are a major source of uncertainty (and aerosol effects (on clouds) are unknown)



Our perspective on what are the most important feedbacks (e.g. low clouds or high clouds) is entirely a function of what is considered the 'system' and its defining output

Stephens and Ellis, 2008

On the what (and why)

- Quantify the processes that determine where clouds and precipitation form, how they form and how much is formed.
- Provide relevant information about the key parameters of these process







The challenge: is it raining or not?



Precip incidence (and amount) from Path Integrated Attenuation (PIA)

• The PIA within a raining column can be estimated by the decrease in surface reflectivity from the clear sky background value:

$$PIA = Z_{sfc,clear} - Z_{sfc,obs}$$


$$PIA = Z_{sfc,clear} - Z_{sfc,obs}$$

Surface reflectivity can be 'easily' deduced over oceans





Extremely sensitive detector of rain - ~0.02 mm/hr

Low cloud -drizzle frequency

Day

Night



Zhien et al., 2008

How Often Does it Rain (Over the Oceans)?



The global mean (oceans) value is ~0.13, i.e., on average, about 13 percent of the clouds observed over our oceans at any time are producing rain.

Stephens et al., 2008

water cloud optical properties

Effective Radius



Optical Thickness



Nakajima and Nakajima (JAS 1995)

Do VIS/NIR and PMW estimates of LWP agree?

 Horvath & Davies (2007) find similar good agreement for TMI LWP versus MODIS (Terra), in general.
However, they see a positive bias in the TMI LWP relative to MODIS (Terra) for partially cloudy scenes, that increases with decreasing cloud fraction. For clear scenes, the bias is +15 g/m².

• Greenwald et al. (2007) find a smaller positive bias (+ 7 g/m²) for AMSR-E relative to MODIS (Aqua), that is a strong function of wind speed and water vapor path (worse at lower wind speeds and higher WVPs).



This is possibly due in part to the "beam-filling effect", and will remain in the Wentz product until a beam-filling correction is instituted for non-raining scenes.